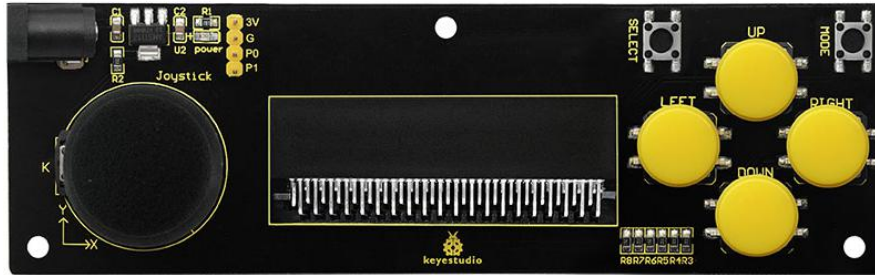


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Keystudio Joystick Breakout Board for micro:bit



Introduction

The BBC micro:bit is a powerful handheld, fully programmable, computer designed by the BBC. It was designed to encourage children to get actively involved in technical activities, like coding and electronics.

It features a 5x5 LED Matrix, two integrated push buttons, a compass, Accelerometer, and Bluetooth.

It supports the PXT graphical programming interface developed by Microsoft and can be used under Windows, MacOS, IOS, Android and many other operating systems without downloading the compiler.

Looking to do more with your BBC micro:bit? Unlock its potential with this Joystick breakout board for the BBC micro:bit!

Keystudio joystick breakout board for micro:bit comes with AMS1117 chip. You can connect the external DC4.75-12V to power for micro:bit

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development board.

It can be used to simulate the mouse or keyboard. Connect the on-board pins 3V、 G、 P0、 P1 to micro:bit main board to get analog serial port, connecting the Bluetooth devices.

This breakout board also consists of 6 buttons and a joystick. Connect the button and joystick to micro:bit pins.

Connect SELECT button to P7; MODE button to P6; UP button to P10; LEFT button to P11; RIGHT button to P9; DOWN button to P8.

Connect joystick X axis to P4; Y axis to P3; Z axis to P5. You can control the external devices by reading the interface states.

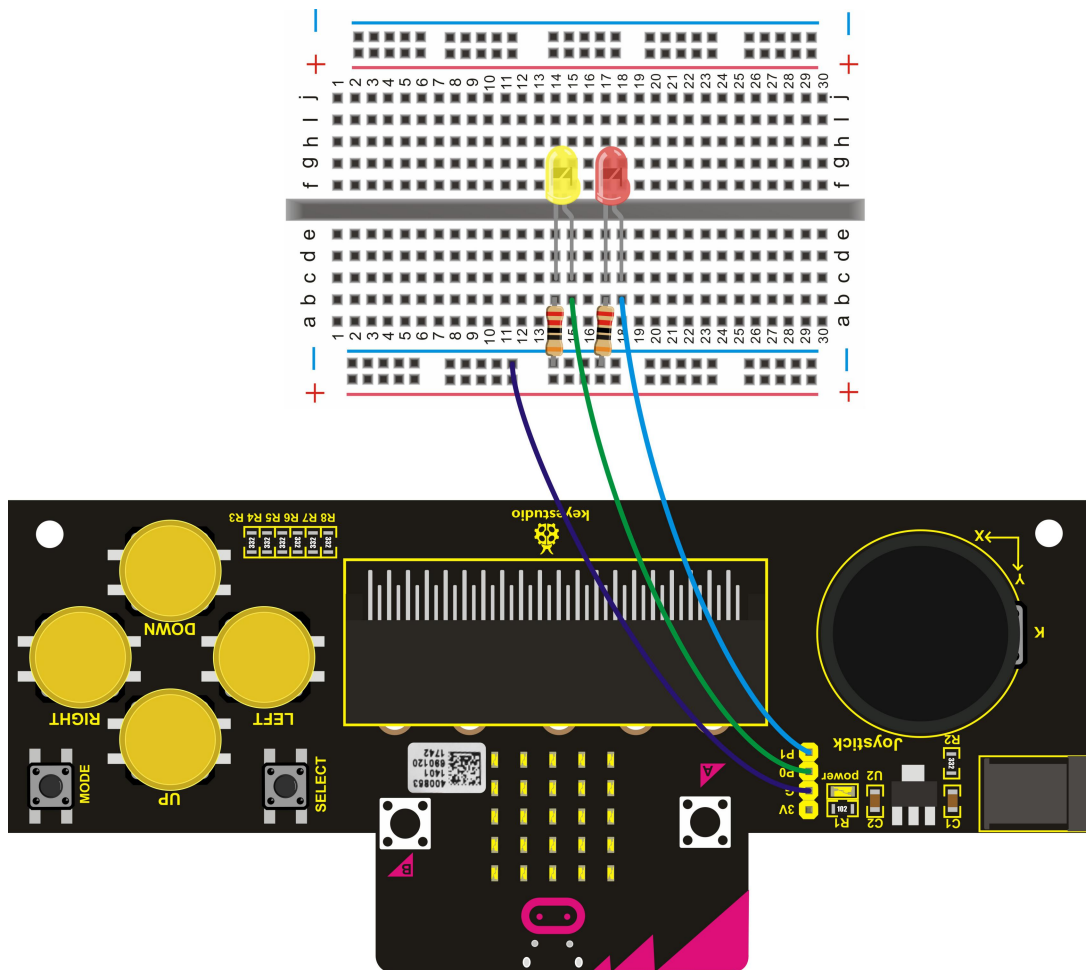
Parameters

- Input Voltage : DC 4.75-12V



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Wiring Diagram



Test Program

You can write the code below on micro:bit MakeCode editor

<https://makecode.microbit.org/#editor>

Downloaded the code you wrote well, send it to your micro:bit main board.

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```
on start
  led enable false

forever
  if (digital read pin P5 == 0)
  then
    digital write pin P1 to 1
  else
    if (digital read pin P6 == 0)
    then
      digital write pin P1 to 1
    else
      if (digital read pin P7 == 0)
      then
        digital write pin P1 to 1
      else
        if (digital read pin P8 == 0)
        then
          digital write pin P1 to 1
        else
          if (digital read pin P9 == 0)
          then
            digital write pin P1 to 1
          else
            if (digital read pin P10 == 0)
            then
              digital write pin P1 to 1
```

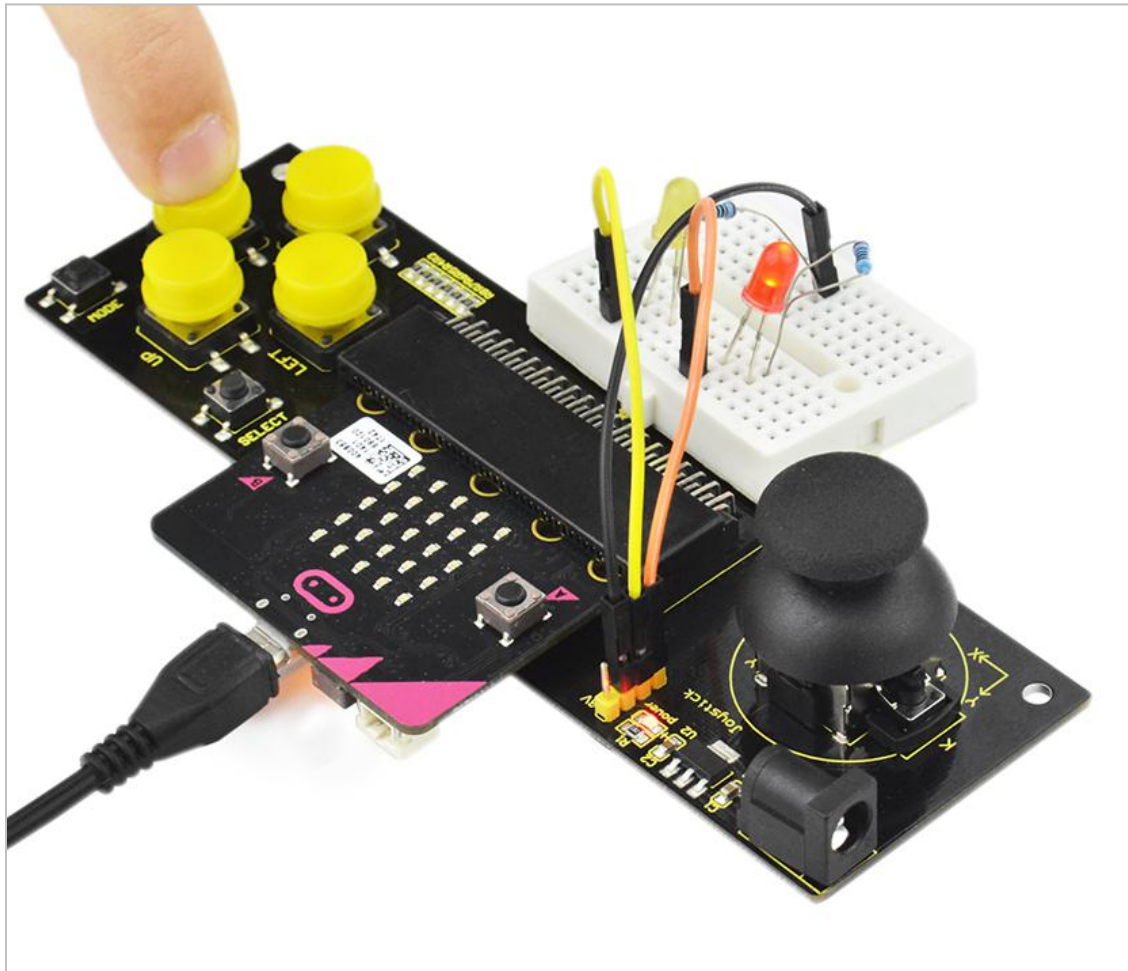
```
else
  if (digital read pin P11 == 0)
  then
    digital write pin P1 to 1
  else
    if (analog read pin P3 < 400)
    then
      digital write pin P0 to 1
    else
      if (analog read pin P3 > 800)
      then
        digital write pin P1 to 1
      else
        if (analog read pin P4 < 400)
        then
          digital write pin P0 to 1
        else
          if (analog read pin P4 > 800)
          then
            digital write pin P1 to 1
          else
            digital write pin P0 to 0
            digital write pin P1 to 0
```

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Test Result

Insert the micro:bit development board into keystudio joystick breakout board, powering up, 2 LEDs will display as below:

- 1) Do not operate both joystick and buttons, 2 LEDs are off.
- 2) Press down any buttons (including joystick Z axis button), red LED is on; release the button, LED will be off.
- 3) Turn Joystick upward, red LED on; joystick downward, yellow LED on; joystick leftward, yellow LED on; joystick rightward, red LED on.



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Shield Experiment

In the experiment, we can insert a micro:bit control board on the shield, upload the corresponding test code, and set it as the Bluetooth host. We take a micro:bit control board, connect to the external device, upload the corresponding test code, set it as a Bluetooth slave. When both micro:bit control boards are powered up, the Bluetooth of two micro:bit control boards connect to the communication. We can control the external devices (such as LED buzzers, etc.) connected to the Bluetooth slave via external devices connected to the Bluetooth host (buttons on shield, joystick).

Here, we use this shield connected to a micro:bit control board to control the movement of a micro:bit smart car (KS0426). When using it, we only use the UP, DOWN, LEFT, RIGHT and SELECT buttons on the shield to control the smart car forward moving, backward moving, left turning, right turning and stopping. The dot matrix of the control board on the smart car displays the current motion status pattern.

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KS0426 Smart Car Resources :

https://wiki.keystudio.com/Ks0426_keyestudio_Micro:bit_Mini_Smart_Robot_Car_Kit_V2

Test Code Of Micro:bit Control Board Connected The Shield:

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```
on start
  radio set group 99
  radio set transmit power 5
  led enable false

forever
  radio send value "X" = analog read pin P4
  radio send value "Y" = analog read pin P3
  radio send value "Z" = digital read pin P5
  radio send value "U" = digital read pin P10
  radio send value "D" = digital read pin P8
  radio send value "L" = digital read pin P11
  radio send value "R" = digital read pin P9
  radio send value "S" = digital read pin P7
  radio send value "M" = digital read pin P6
```

Test Code Of Micro : bit Control Board On KS0426 Smart Car:

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```
on radio received name value
  if name = "U" then
    set U1 to value
    if U1 = 0 then
      call front
      show leds
    else if name = "D" then
      set D1 to value
      if D1 = 0 then
        call back
        show leds
      else if name = "L" then
        set L1 to value
        if L1 = 0 then
          call left
          show leds
        else if name = "R" then
          set R1 to value
          if R1 = 0 then
            call right
            show leds
        else if name = "S" then
          set S1 to value
          if S1 = 0 then
            call stop
            show leds

function front
  set led duty cycle LED1 to 0 67
  set led duty cycle LED2 to 100 67
  set led duty cycle LED3 to 0 67
  set led duty cycle LED4 to 100 67

function back
  set led duty cycle LED1 to 100 67
  set led duty cycle LED2 to 100 67
  set led duty cycle LED3 to 100 67
  set led duty cycle LED4 to 100 67

function stop
  set led duty cycle LED1 to 0 67
  set led duty cycle LED2 to 0 67
  set led duty cycle LED3 to 0 67
  set led duty cycle LED4 to 0 67

function left
  set led duty cycle LED1 to 100 67
  set led duty cycle LED2 to 50 67
  set led duty cycle LED3 to 0 67
  set led duty cycle LED4 to 50 67

function right
  set led duty cycle LED1 to 0 67
  set led duty cycle LED2 to 50 67
  set led duty cycle LED3 to 100 67
  set led duty cycle LED4 to 50 67

on start
  radio set group 99
  led enable true
  clear screen
  init 67 0
```

Resource

<https://fs.keystudio.com/KS0296>

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